

2704: Signals and Systems

Homework #4 Solutions

19. (a)
 $y'(t) + 5y(t) = x(t)$

The standard solution for a First-Order Differential Equation is:

$$y(t) = Ke^{-at}u(t), \text{ where } a = 5.$$

To find the impulse response,

$$h'(t) + 5h(t) = \delta(t)$$

$$h(0^+) - h(0^-) + a \int_{0^-}^{0^+} h(t) dt = \int_{0^-}^{0^+} \delta(t) dt = 1$$

$$\text{Since } \int_{0^-}^{0^+} h(t) dt = 0$$

$$h(0^+) - h(0^-) = 1$$

Since we are looking at the impulse response, $h(0^-) = 0$ since nothing exists before $t = 0$.

$$\text{This gives us } h(0^+) = 1 = Ke^{-a(0)} = K$$

This finally gives us:

$$h(t) = e^{-5t}u(t)$$

(b)

$$y''(t) + 6y'(t) + 4y(t) = x(t)$$

$$h''(t) + 6h'(t) + 4h(t) = \delta(t)$$

$$\therefore h(t) = (K_1e^{-at} + K_2e^{-bt}) \cdot u(t)$$

$$h'(0^+) - h'(0^-) + 6[h(0^+) - h(0^-)] + 4 \int_{0^-}^{0^+} h(t) dt = \int_{0^-}^{0^+} \delta(t) dt = 1$$

We know that the impulse response cannot contain an impulse because its second derivative would be a triplet and there is no triplet excitation. We also know that the response cannot be discontinuous at time $t = 0$ because if it were the second derivative would be a doublet and there is no doublet excitation. Therefore,

$$h'(0^+) - h'(0^-) = 1 \rightarrow h'(0^+) = 1$$

Therefore,

$$\lambda^2 + 6\lambda + 4 = 0 \rightarrow \lambda = [-0.764, -5.24] \therefore h'(t) = -0.764K_1e^{-0.764t} - 5.24K_2e^{-5.24t}$$

$$h'(0^+) = 1 = -5.24K_1 - 0.76K_2 = 1$$

We can also show:

$$h(0^+) = 0 = K_1e^{-5.24(0)} + K_2e^{-0.76(0)} = K_1 + K_2 \rightarrow K_1 = -K_2 \therefore K_1 = -0.2236, K_2 = 0.2236$$

Thus, the total response is:

$$h(t) = 0.2236(e^{-0.76t} - e^{-5.24t})u(t)$$

(c)

$$2y'(t) + 3y(t) = x'(t)$$

Thus, we know $h_h(t) = K_h e^{-\frac{3}{2}t}$. The impulse response will be of the form

$$h(t) = K_h e^{-\frac{3}{2}t} u(t) + K_i \delta(t)$$

Integrating from 0^- to 0^+ ,

$$2[h(0^+) - h(0^-)] + 3 \int_{0^-}^{0^+} h(t) dt = x(0^+) - x(0^-) = 0 = 2K_h + 3K_i$$

Integrating a second time from 0^- to 0^+ ,

$$2 \int_{0^-}^{0^+} h(t) dt = \int_{0^-}^{0^+} \delta(t) dt = 1 \rightarrow 2K_i = 1 \therefore K_i = \frac{1}{2} \therefore K_h = -\frac{3}{4}$$

Therefore,

$$h(t) = -\frac{3}{4} e^{-\frac{3}{2}t} u(t) + \frac{1}{2} \delta(t)$$

(d)

$$4y'(t) + 9y(t) = 2x(t) + x'(t)$$

Thus, we know $h_h(t) = K_h e^{-\frac{9}{4}t}$, and the impulse response is of the form

$$h(t) = K_h e^{-\frac{9}{4}t} u(t) + K_i \delta(t)$$

Integrating from 0^- to 0^+ ,

$$4[h(0^+) - h(0^-)] + 9 \int_{0^-}^{0^+} h(t) dt = 2 \int_{0^-}^{0^+} \delta(t) dt + x(0^+) - x(0^-) = 2 = 4K_h + 9K_i$$

Integrating a second time from 0^- to 0^+ ,

$$4 \int_{0^-}^{0^+} h(t) dt = 1 \rightarrow 4K_i = 1 \therefore K_i = \frac{1}{4} \therefore K_h = -\frac{1}{16}$$

Therefore,

$$h(t) = -\frac{1}{16} e^{-\frac{9}{4}t} u(t) + \frac{1}{4} \delta(t)$$

23)

$$h(t) = 4e^{-4t}u(t)$$

$$x(t) = \text{rect}\left(2\left(t - \frac{1}{4}\right)\right) = \text{rect}\left(\frac{4t-1}{2}\right)$$

If you are unsure how this *rect* function will look, remember that *rect*(*t*) is on at $-\frac{1}{2}$ to $+\frac{1}{2}$, so if we just check the arguments for those values, we see this *rect* is one high for $t = [0, 0.5]$.

$$y(t) = h(t) * x(t) = \int_{-\infty}^{\infty} h(\lambda)x(t-\lambda)d\lambda$$

Since we are dealing with a *rect* and an infinite length function, we will have three ranges:

- 1) $(t + 0.5) < 0$: No intersection
- 2) $0 \leq t \leq 0.5$: Entering
- 3) $t > 0.5$: Fully intersecting

$0 \leq t \leq 0.5$

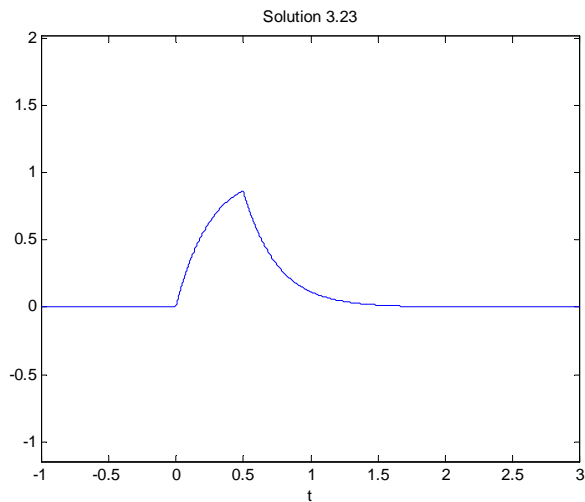
$$y_1(t) = \int_0^t 4e^{-4\lambda} d\lambda = -e^{-4\lambda} \Big|_0^t = 1 - e^{-4t}$$

$t > 0.5$

$$y_2(t) = \int_{t-0.5}^t 4e^{-4\lambda} d\lambda = -e^{-4\lambda} \Big|_{t-0.5}^t = e^{-4t+2} - e^{-4t}$$

Therefore

$$y(t) = \begin{cases} 0 & o.w. \\ 1 - e^{-4t} & 0 \leq t \leq 0.5 \\ e^{-4t+2} - e^{-4t} & t > 0.5 \end{cases}$$



24)

$$h(t) = \delta(t) - 4e^{-4t}u(t)$$

$$x(t) = \text{rect}\left(2\left(t - \frac{1}{4}\right)\right) = \text{rect}\left(\frac{4t-1}{2}\right)$$

We can quickly solve this problem by using the solution above. We know that the only difference is that we will be retaining a copy of the original input (the *rect* function) and adding that to a flipped version of the result.

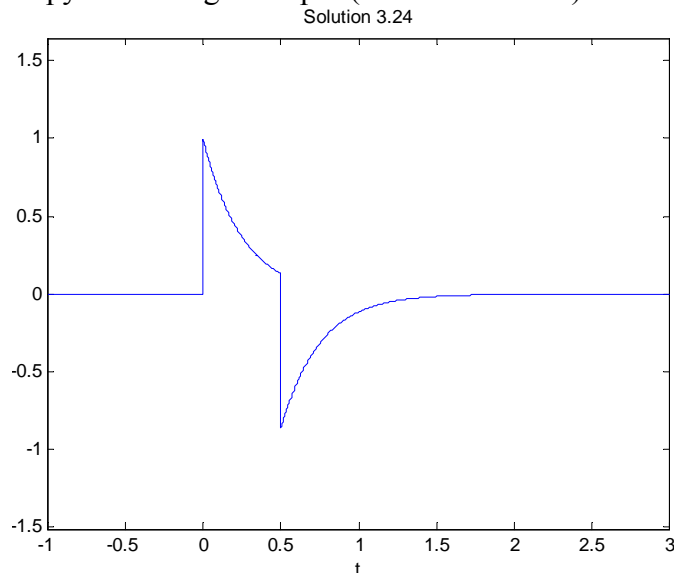
Recall:

$$y_{3.23}(t) = \begin{cases} 0 & o.w. \\ 1 - e^{-4t} & 0 \leq t \leq 0.5 \\ e^{-4t+2} - e^{-4t} & t > 0.5 \end{cases}$$

$$y(t) = x(t) - y_{3.23}(t)$$

Therefore,

$$y(t) = \begin{cases} 0 & o.w. \\ e^{-4t} & 0 \leq t \leq 0.5 \\ e^{-4t} - e^{-4t+2} & t > 0.5 \end{cases}$$

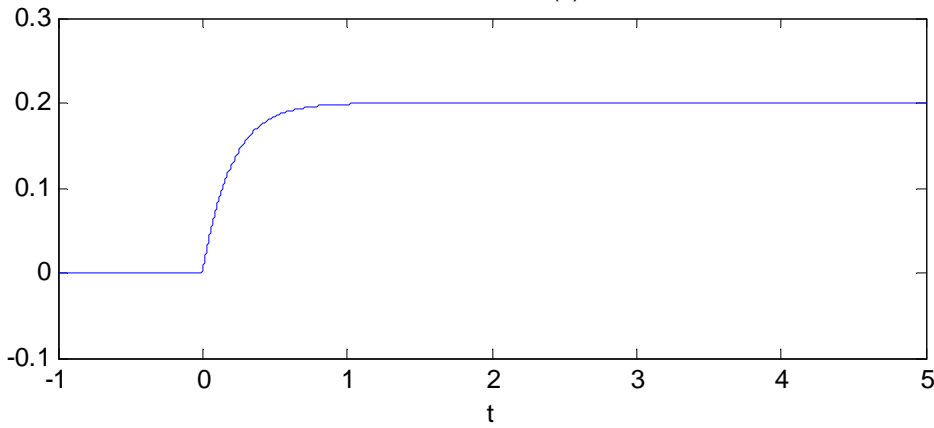


31)

(a) $h(t) = e^{-5t} u(t)$

$$h_{-1} = \int_{-\infty}^{\infty} e^{-5\lambda} u(\lambda) u(t - \lambda) d\lambda = \int_0^t e^{-5\lambda} d\lambda = \frac{1 - e^{-5t}}{5} u(t)$$

Solution 3.31(a)

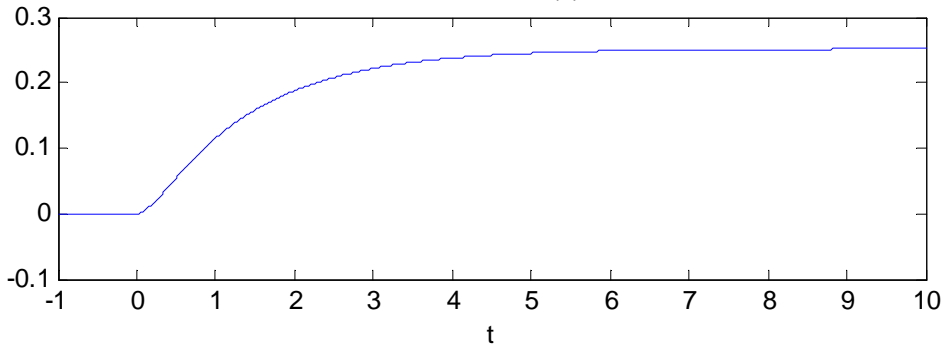


(b) $h(t) = 0.2236 (e^{-0.76t} - e^{-5.24t}) u(t)$

$$h_{-1} = \int_{-\infty}^{\infty} 0.2236 (e^{-0.76\lambda} - e^{-5.24\lambda}) u(\lambda) u(t - \lambda) d\lambda = \int_0^t 0.2236 (e^{-0.76\lambda} - e^{-5.24\lambda}) d\lambda$$

$$= 0.2236 (1.316 (1 - e^{-0.76t}) - 0.1912 (1 - e^{-5.23t})) \cdot u(t)$$

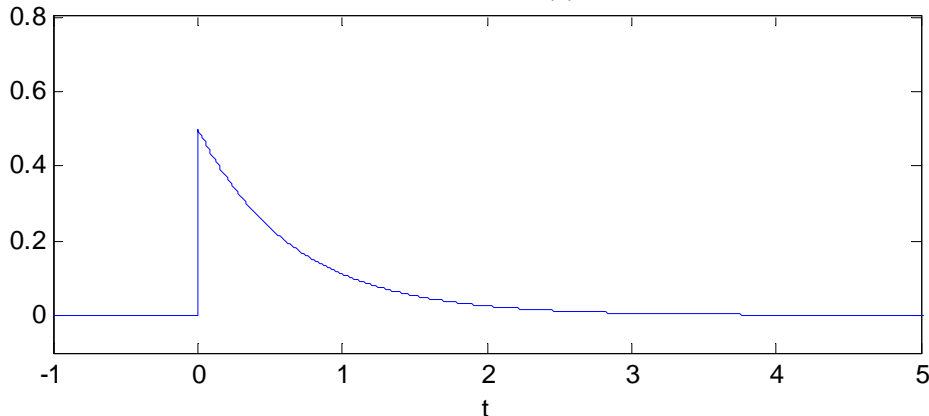
Solution 3.31(b)



(c) $h(t) = \frac{1}{2} \delta(t) - \frac{3}{4} e^{-\frac{3}{2}t} u(t)$

$$h_{-1} = \int_{-\infty}^{\infty} \left[\frac{1}{2} \delta(\lambda) - \frac{3}{4} e^{-\frac{3}{2}\lambda} u(\lambda) \right] u(t - \lambda) d\lambda = \frac{1}{2} - \frac{3}{4} \int_0^t e^{-\frac{3}{2}\lambda} d\lambda = \frac{1}{2} u(t) + \frac{e^{-\frac{3}{2}t} - 1}{2} u(t) = \frac{1}{2} e^{-\frac{3}{2}t} u(t)$$

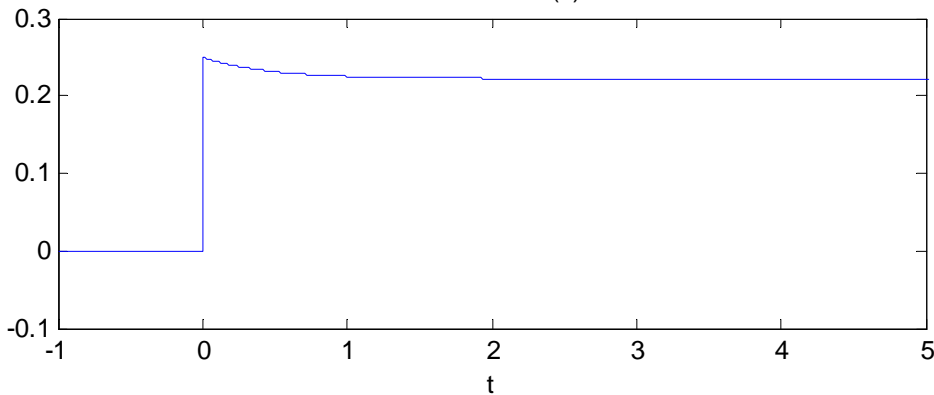
Solution 3.31(c)



$$(d) h(t) = \frac{1}{4} \delta(t) - \frac{1}{16} e^{-\frac{9}{4}t} u(t)$$

$$h_{-1} = \int_{-\infty}^{\infty} \left[\frac{1}{4} \delta(\lambda) - \frac{1}{16} e^{-\frac{9}{4}\lambda} u(\lambda) \right] u(t-\lambda) d\lambda = \frac{1}{4} - \frac{1}{16} \int_0^t e^{-\frac{9}{4}\lambda} d\lambda = \frac{1}{4} u(t) + \frac{e^{-\frac{9}{4}t} - 1}{36} u(t) = \frac{2}{9} u(t) + \frac{1}{36} e^{-\frac{9}{4}t} u(t)$$

Solution 3.31(d)



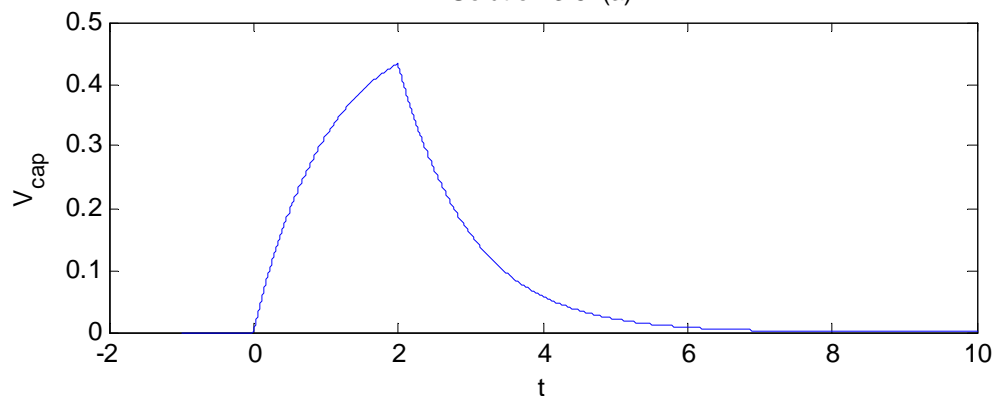
54) From the example in the lecture, we know that for an RC circuit with the voltage measured across C the impulse response is:

$$h(t) = \frac{1}{RC} e^{-\frac{1}{RC}t} u(t) = \frac{1}{(10k\Omega)(100\mu F)} e^{-\frac{1}{(10k\Omega)(100\mu F)}t} u(t) = e^{-t} u(t)$$

(a) The pulse can be written as $V_{in}(t) = \frac{1}{2} \text{rect}\left(\frac{t-1}{2}\right)$

$$V_{cap}(t) = \frac{1}{2} \int_{-\infty}^{\infty} e^{-\lambda} u(\lambda) \text{rect}\left(\frac{(t-\lambda)-1}{2}\right) d\lambda = \begin{cases} 0 & t < 0 \\ \frac{1-e^{-t}}{2} & 0 \leq t \leq 2 \\ \frac{e^{-t+2} - e^{-t}}{2} & t > 2 \end{cases}$$

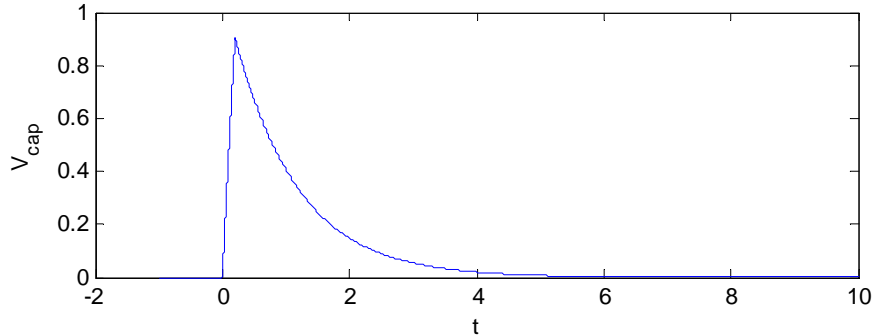
Solution 3.54(a)



(b) The pulse can be written as $V_{in}(t) = 5 \text{rect}\left(\frac{t-0.1}{0.2}\right)$

$$V_{cap}(t) = 5 \int_{-\infty}^{\infty} e^{-\lambda} u(\lambda) \text{rect}\left(\frac{(t-\lambda)-0.1}{0.2}\right) d\lambda = \begin{cases} 0 & t < 0 \\ 5 - 5e^{-t} & 0 \leq t \leq 0.2 \\ 5(e^{-t+0.2} - e^{-t}) & t > 0.2 \end{cases}$$

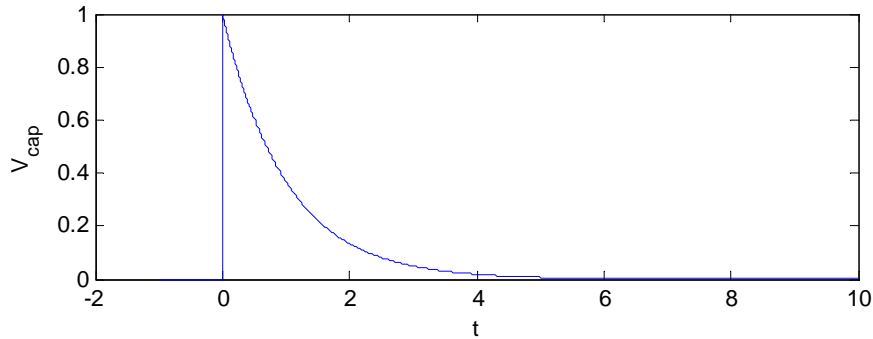
Solution 3.54(b)



(c) The pulse can be written as $V_{in}(t) = 50 \text{rect}\left(\frac{t-0.001}{0.002}\right)$

$$V_{cap}(t) = 500 \int_{-\infty}^{\infty} e^{-\lambda} u(\lambda) \text{rect}\left(\frac{(t-\lambda)-0.001}{0.002}\right) d\lambda = \begin{cases} 0 & t < 0 \\ 500 - 500e^{-t} & 0 \leq t \leq 0.002 \\ 500(e^{-t+0.002} - e^{-t}) & t > 0.002 \end{cases}$$

Solution 3.54(c)

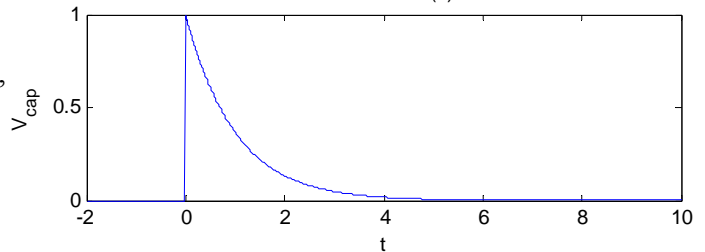


(d) 2×10^{-6} The pulse can be written as $V_{in}(t) = 500 \times 10^3 \text{rect}\left(\frac{t-10^{-6}}{2 \times 10^{-6}}\right)$

$$V_{cap}(t) = 500 \times 10^3 \int_{-\infty}^{\infty} e^{-\lambda} u(\lambda) \text{rect}\left(\frac{(t-\lambda)-10^{-6}}{2 \times 10^{-6}}\right) d\lambda = \begin{cases} 0 & t < 0 \\ 500 \times 10^3 - 500 \times 10^3 e^{-t} & 0 \leq t \leq 2 \times 10^{-6} \\ 500 \times 10^3 (e^{-t+2 \times 10^{-6}} - e^{-t}) & t > 2 \times 10^{-6} \end{cases}$$

Solution 3.54(d)

From these results, we see that as the voltage pulse tends towards an impulse, the output tends towards the impulse response (as expected).



56)

(a)

$$y(t) = \frac{d(t)}{R}$$

$$\frac{d}{dt} \left(\underbrace{Ad(t)}_{\text{volume}} \right) = x(t) - y(t)$$

$$Ad'(t) = x(t) - \frac{d(t)}{R}$$

$$Ad'(t) + \frac{d(t)}{R} = x(t)$$

(b)

Find when $d'(t) = 0$.

$$d(t) = Rx(t) = 10 \frac{s}{m^2} \times 0.05 \frac{m^3}{s} = 0.5m$$

(c)

Dumping 1 m^3 of water into an empty tank is exciting this system with a unit impulse of water inflow. The impulse response, $h(t)$, of the system is the solution of

$$Ah'(t) + \frac{h(t)}{R} = \delta(t) \rightarrow h(t) = Ke^{-\frac{t}{AR}}u(t)$$

We can find K by finding the initial water depth in response to 1 m^3 being suddenly dumped in. The surface area is 0.7854 m^2 . Therefore the initial depth is 1.273 m and

$$h(t) = 1.273e^{-\frac{t}{AR}}u(t)$$

(d)

The response to a step of flow is the convolution of the impulse response with the step excitation

$$d(t) = h(t) * x(t) = 1.273e^{-\frac{t}{AR}}u(t) * 0.2u(t)$$

$$d(t) = 0.2546 \int_{-\infty}^{\infty} e^{-\frac{\lambda}{AR}}u(\lambda)u(t-\lambda)d\lambda = 0.2546 \int_0^t e^{-\frac{\lambda}{AR}}d\lambda = -0.2546AR \left(1 - e^{-\frac{t}{AR}} \right)$$

Therefore:

$$d(t) = 2 \left(1 - e^{-\frac{t}{7.854}} \right) u(t) = 1.5m \rightarrow t = 10.886s$$

61)

(a) Summing forces:

$$f(t) - mg \sin(\theta) - k_f y'(t) = m y''(t) \rightarrow f(t) = mg \sin(\theta) + k_f y'(t) + m y''(t)$$

(b)

The zero-excitation response can be found by setting the force, $f(t)$, to zero:

$$-mg \sin(\theta) = k_f y'(t) + m y''(t)$$

Thus, $y_h(t) = K_{h1} + K_{h2} e^{-\frac{k_f t}{m}}$. The particular solution must be in the form of a linear function of t , to satisfy the differential equation. Choosing the form,

$$y_p(t) = K_p t$$

And solving, $K_p = -\frac{mg}{k_f} \sin(\theta)$. Thus, the total zero-excitation response is

$$y(t) = y_h(t) + y_p(t) = K_{h1} + K_{h2} e^{-\frac{k_f t}{m}} - \left(\frac{mg}{k_f} \sin(\theta) \right) t$$

Using the initial conditions,

$$y(0) = 0 = K_{h1} + K_{h2}$$

and

$$y'(0) = 10 = -\frac{k_f}{m} K_{h2} - \frac{mg}{k_f} \sin(\theta)$$

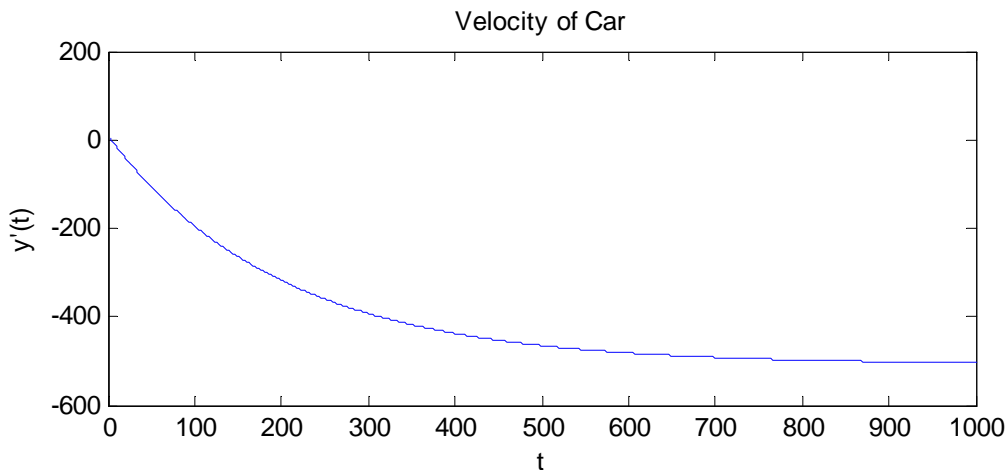
Solving yields:

$$K_{h2} = -\left(\frac{m}{k_f} \right)^2 g \sin(\theta) - \frac{m}{k_f} 10 = -1.0146 \times 10^5 - 2000 = -1.0346 \times 10^5$$

$$K_{h1} = 1.0346 \times 10^5$$

$$y(t) = 1.0346 \times 10^5 \left(1 - e^{-\frac{t}{200}} \right) - 507.28 t$$

$$y'(t) = \frac{1.0346 \times 10^5}{200} \left(e^{-\frac{t}{200}} \right) - 507.28 = 517.28 \left(e^{-\frac{t}{200}} - 1 \right) + 10$$



(c)

We can write:

$$x(t) = f(t) - mg \sin(\theta) = 200 - mg \sin(\theta) = k_f y'(t) + my''(t)$$

Then the impulse response of the system is the solution of:

$$mh''(t) + k_f h'(t) = \delta(t)$$

which is of the form:

$$h(t) = \left(K_{h1} + K_{h2} e^{-\frac{k_f t}{m}} \right) u(t)$$

Integrating both sides of the equation from 0^- to 0^+ ,

$$\begin{aligned} mh'(0^+) + k_f h(0^+) &= 1 = m \left(-\frac{k_f}{m} K_{h2} \right) + k_f (K_{h1} + K_{h2}) \\ &= -k_f K_{h2} + k_f (K_{h1} + K_{h2}) = k_f K_{h1} \therefore K_{h1} = \frac{1}{k_f} \end{aligned}$$

Integrating a second time gives us,

$$mh(0^+) = 0 = m(K_{h1} + K_{h2}) \rightarrow K_{h2} = -K_{h1} = -\frac{1}{k_f}$$

Therefore, the impulse response is,

$$h(t) = \frac{1 - e^{-\frac{k_f t}{m}}}{k_f} u(t)$$

Recall at the beginning we defined the excitation as,

$$x(t) = 200 - mg \sin(\theta)$$

For convenience sake, we will assume the car was held in place prior to the 200-newton push at time $t = 0$, making the excitation:

$$x(t) = (200 - mg \sin(\theta))u(t)$$

Therefore,

$$y(t) = x(t) * h(t) = [200 - mg \sin(\theta)]u(t) * \frac{1 - e^{-\frac{k_f t}{m}}}{k_f} u(t) = \frac{200 - mg \sin(\theta)}{k_f} \int_0^t \left(1 - e^{-\frac{k_f \lambda}{m}} \right) d\lambda$$

Solving gives us,

$$y(t) = \frac{200 - mg \sin(\theta)}{k_f} \left[t + \frac{m}{k_f} e^{-\frac{k_f t}{m}} - \frac{m}{k_f} \right]$$

Terminal velocity is defined as $\lim_{t \rightarrow \infty} \frac{dy(t)}{dt}$. So to find the terminal velocity:

$$\lim_{t \rightarrow \infty} \frac{dy(t)}{dt} = \lim_{t \rightarrow \infty} \left\{ \left(\frac{200 - mg \sin(\theta)}{k_f} \right) \left[1 - e^{-\frac{k_f t}{m}} \right] \right\} = \frac{200 - mg \sin(\theta)}{k_f} = \frac{200 - 2536.43}{5} = -467.3 \text{ m/s}$$