

ECE4634
Introduction to
Digital Communications
Fall 2007

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Lecture #26: Bandpass
Receivers



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Receiver



- Assuming a benign channel, at the receiver we observe the transmitted signal plus additive white Gaussian noise

$$r(t) = x(t) + n(t)$$

- Both the transmitted signal $x(t)$ and the noise signal $n(t)$ are *a priori* unknown.
- Since there are a finite number of possible transmitted signals, the job of the receiver is to determine the most likely transmitted signal based on the observed receive signal

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Receiver (cont.)



- Using the signal space representation of modulation the receiver consists of
 - Correlating the received signal with each basis function
 - Sampling each correlator output to create a single point in K -dimensional space
 - Creating the symbol estimate as the closest symbol in terms of Euclidean distance
- To maximize SNR we use *matched filters*
 - Correlation with the basis function can be viewed as matched filtering

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Received Signal (cont.)



- Similarly on the Quadrature branch

$$\begin{aligned} \int_0^T r(t) \sin(2\pi f_c t) dt &= \int_0^T \{x(t) \cos(2\pi f_c t) \sin(2\pi f_c t) - y(t) \sin^2(2\pi f_c t)\} dt \\ &= \int_0^T A_x \frac{1}{2} \underbrace{\sin(2\pi f_c t) \cos(2\pi f_c t)}_{\text{orthogonal}} dt - \int_0^T B_y \frac{1}{2} \left[1 - \underbrace{\cos(4\pi f_c t)}_{\text{eliminated by int.}} \right] dt \\ &\approx -\frac{BT}{2} \end{aligned}$$

- Thus, if we negate the Q-channel output, we have a scaled version of the signal space point.

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Matched Filtering



- The previous receiver structure is also an implementation of the matched filter
- Consider BPSK

$$s_1(t) = \Pi\left(\frac{t-T}{T}\right) \cos(2\pi f_c t)$$

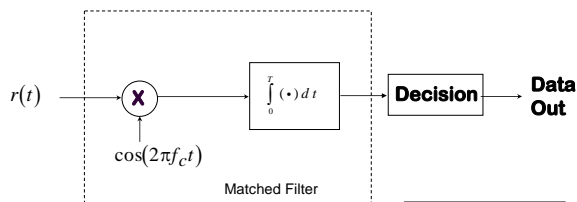
$$s_2(t) = -\Pi\left(\frac{t-T}{T}\right) \cos(2\pi f_c t)$$

- Thus, we are modulating the pulse $\Pi\left(\frac{t-T}{T}\right) \cos(2\pi f_c t)$
- The receiver should simply correlate with this pulse to maximize SNR

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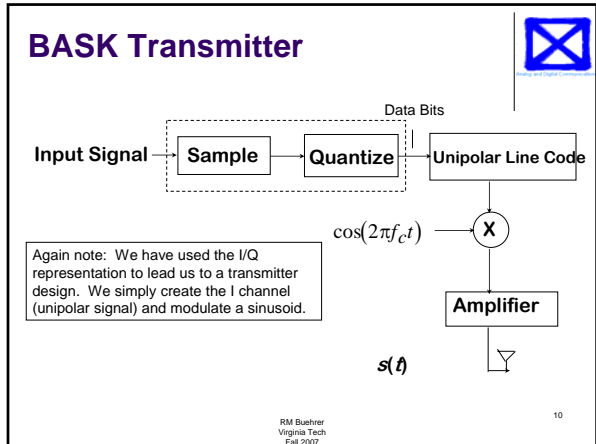
BPSK Receiver

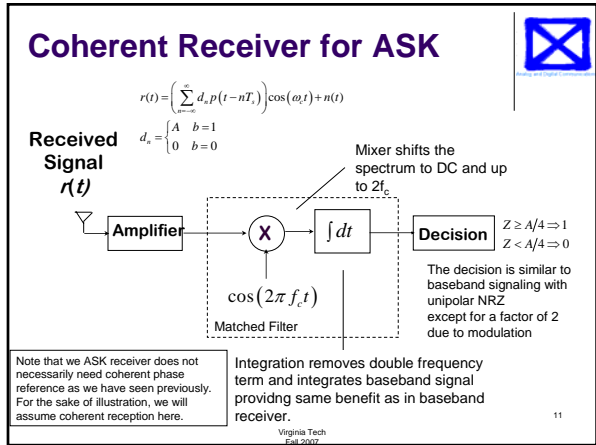


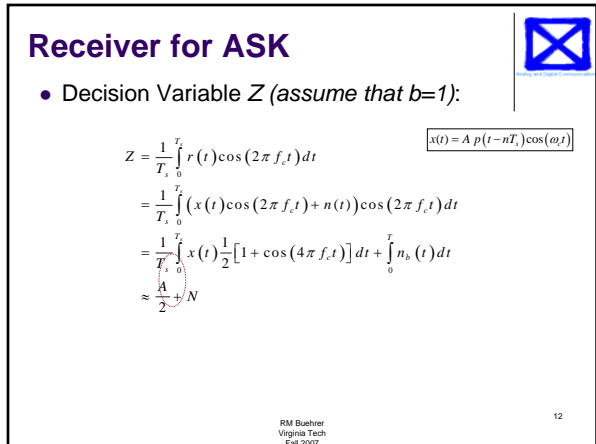
The combination of a mixer and integrator are a matched filter for BPSK with square pulses

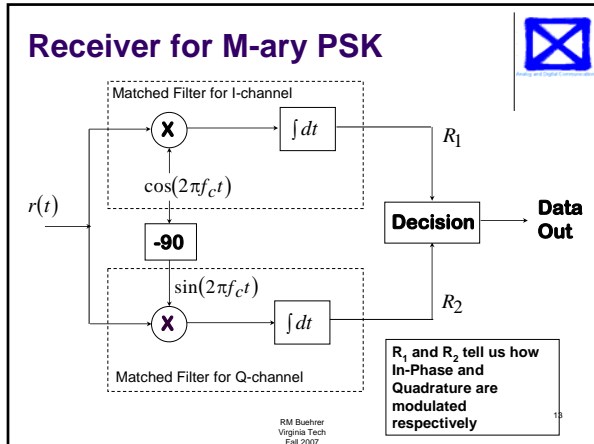
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Receiver for MPSK

- Decision Variable $Z=R_1+jR_2$

$$R_1 = \frac{1}{T_s} \int_0^{T_s} r(t) \cos(2\pi f_c t) dt$$

$$= \frac{1}{T_s} \int_0^{T_s} (x(t) \cos(2\pi f_c t) - y(t) \sin(2\pi f_c t) + n(t)) \cos(2\pi f_c t) dt$$

$$= \frac{1}{T_s} \int_0^{T_s} x(t) \frac{1}{2} [1 + \cos(4\pi f_c t)] dt - \frac{1}{T_s} \int_0^{T_s} y(t) \sin(2\pi f_c t) \cos(2\pi f_c t) dt + \int_0^{T_s} n_i(t) dt$$

$$\approx \frac{A_x}{2} + N_i$$

$$R_2 = \frac{1}{T_s} \int_0^{T_s} r(t) \sin(2\pi f_c t) dt$$

$$= \frac{1}{T_s} \int_0^{T_s} (x(t) \cos(2\pi f_c t) - y(t) \sin(2\pi f_c t) + n(t)) \sin(2\pi f_c t) dt$$

$$= \frac{1}{T_s} \int_0^{T_s} x(t) \cos(2\pi f_c t) \sin(2\pi f_c t) dt - \frac{1}{T_s} \int_0^{T_s} y(t) \frac{1}{2} [1 - \cos(4\pi f_c t)] dt + \int_0^{T_s} n_q(t) dt$$

$$\approx \frac{B_x}{2} + N_q$$

$A_x = \cos(\theta_1) \cos(\theta_2) \dots \cos(\theta_M)$
 $B_x = \sin(\theta_1) \sin(\theta_2) \dots \sin(\theta_M)$

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Pulse shaping

- The transmit signal for ASK with pulse shaping is

$$x(t) = \left(\sum_{n=-\infty}^{\infty} d_n p(t-nT_s) \right) \cos(\omega_c t)$$

$$d_n = \begin{cases} A & b=1 \\ 0 & b=0 \end{cases}$$
 - Where $p(t)$ is now any pulse shape rather than a square pulse.
- The transmit signal for PSK with pulse shaping is

$$x(t) = \left(\sum_{n=-\infty}^{\infty} A_n p(t-nT_s) \right) \cos(\omega_c t) - \left(\sum_{n=-\infty}^{\infty} B_n p(t-nT_s) \right) \sin(\omega_c t)$$

$$A_n = \cos(\theta_n) \quad \theta_n \in \left\{ 0, \frac{\pi}{M}, \frac{2\pi}{M}, \dots, \frac{(M-1)\pi}{M} \right\}$$

$$B_n = \sin(\theta_n)$$

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Pulse Shaping Receiver



- Again we must use a receiver matched to the basis functions which includes the pulse shape
- For BPSK or M -ary ASK we have a single matched filter

$$p(t) \cos(2\pi f_c t)$$

- For M -PSK we have two matched filters

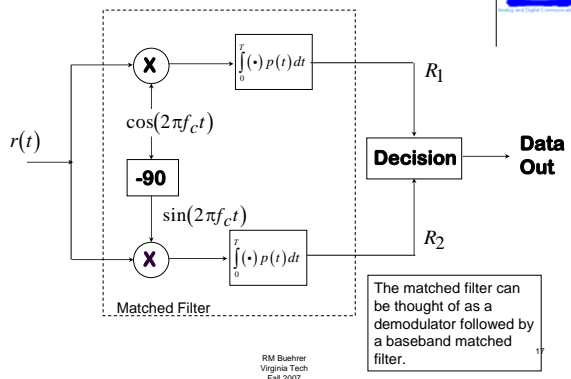
$$p(t) \cos(2\pi f_c t)$$

$$p(t) \sin(2\pi f_c t)$$

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Ex: Receiver for M-ary PSK



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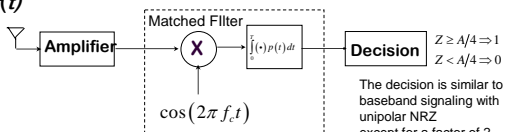
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Ex: Coherent Receiver for ASK



$$r(t) = \left(\sum_{n=-\infty}^{\infty} d_n p(t-nT_s) \right) \cos(\omega_c t) + n(t)$$

Received Signal $r(t)$
 $d_n = \begin{cases} A & b=1 \\ 0 & b=0 \end{cases}$



The decision is similar to baseband signaling with unipolar NRZ except for a factor of 2 due to modulation

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Inter-symbol Interference



- Recall that for zero ISI we must satisfy the Nyquist criterion
- Pulses such as square pulses, sinc pulses, and raised cosine pulses satisfy this criterion
- However
 - Square pulses require too much bandwidth
 - Sinc pulses require infinite time delay
- Truncated sinc pulses are a practical alternative
- Truncated raised cosine pulses are even more practical since they can be truncated to shorter lengths
- These can also be used with bandpass modulation

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Raised Cosine pulses and Matched Filters



- If we transmit raised cosine pulses, in order to maximize SNR we must use a matched filter (i.e., a raised cosine pulse filter) at the receiver
- If we apply a raised cosine pulse filter twice (once on transmit and once at the receiver) the result will not be a raised cosine pulse and thus will have ISI
- To avoid this, we must apply a square root raised cosine pulse ($p_{sq}(t)$) at the transmitter and at the receiver

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Square Root Raised Cosine Filters



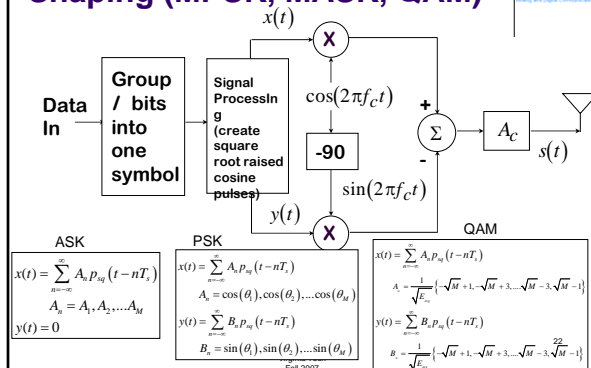
- We actually want the zero ISI to occur at the receiver
 - We want the spectrum out of the matched filter to have a raised cosine shape
- Therefore we use:
 - Pulse shape at transmitter: $S(f) = \sqrt{P_{rc}(f)}$
 - Pulse shape of matched filter: $H(f) = \sqrt{P_{rc}(f)}$
- Overall result is a raised cosine pulse at output of receiver matched filter

$$R(f) = S(f)H(f) = \sqrt{P_{rc}(f)}\sqrt{P_{rc}(f)} = P_{rc}(f)$$

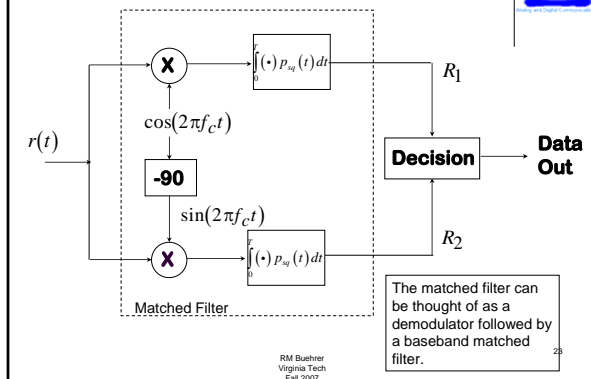
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Generic Transmitter with Pulse Shaping (MPSK, MASK, QAM)



Receiver for M-ary PSK



Superheterodyne Receivers

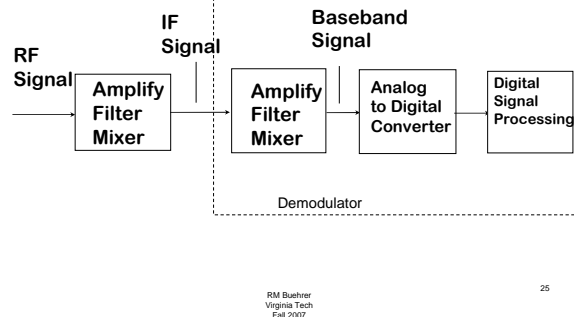


- Edwin Armstrong (1918)
- Demodulation is accomplished in two stages
- It is very difficult to demodulate a signal exactly to zero frequency from the radio frequency (RF)
 - Typical RF values: 100 kHz - 30 GHz
- An intermediate frequency (IF) stage is introduced
 - Typical IF values: 50 kHz - 100 MHz (70MHz very common)

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Superheterodyne Receiver



Summary



- The receiver design can be directly determined from the signal space representation
- The receiver must correlate the received signal with each of the basis functions (i.e., matched filters)
- The resulting values form a received point in the K -dimensional signal space which must be mapped to the nearest symbol
- This operation can also be thought of as demodulation followed by low-pass filtering
- Pulse shaping is readily incorporated into this framework as we have seen

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